



Industrial and Systems Engineering
Texas A&M University

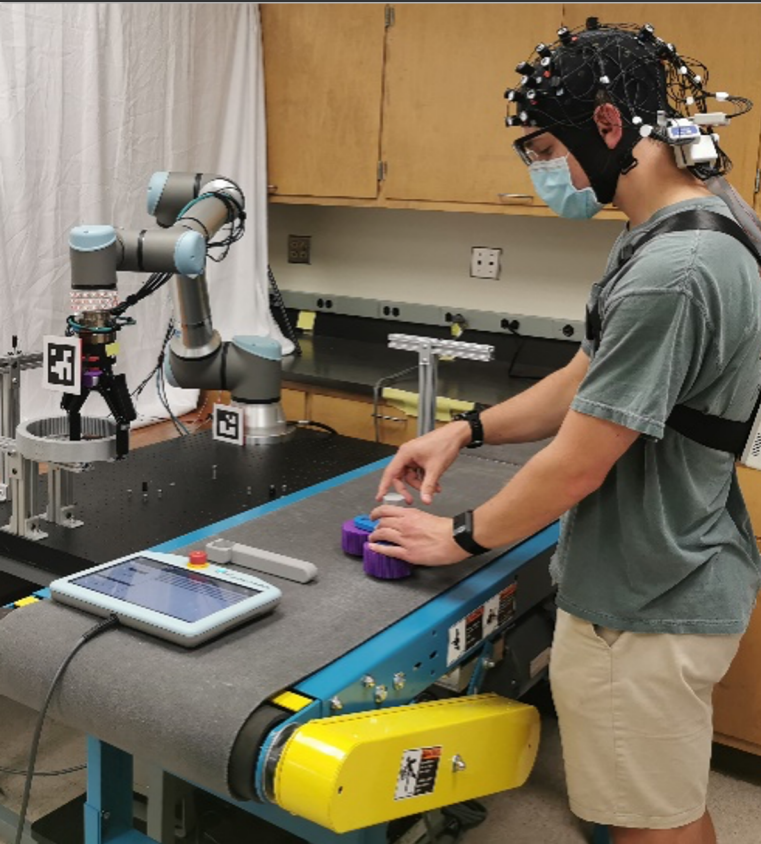
Multimodal Bio-Behavioral Approaches to Study Trust in Human-Robot Collaboration

4th Annual Workshop on Novel and Emerging Test Methods & Metrics for Effective HRI

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Current Methods and Challenges



- Subjective trust measures
 - Invasive
 - Biased
 - Discrete and sparse
- Lack of human centered metrics
 - Human performance
 - Human behavior
 - Physical and cognitive states
- Hardcoded interaction

Need for New Perspectives

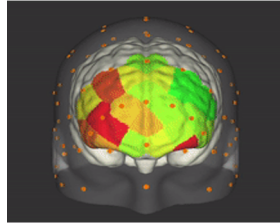


Multimodal Physiological Measurements



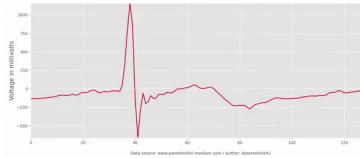
fNIRS

Measures Brain Activity



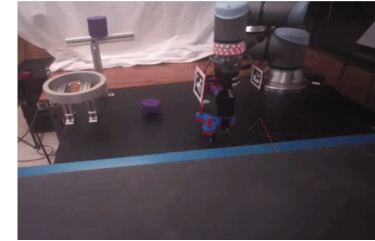
Actiheart

Measures Heart Rate Variability



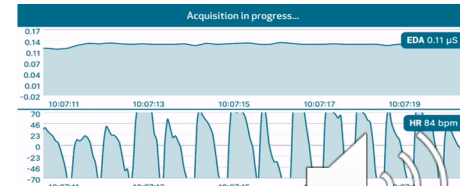
Tobii Pro

Measures Pupil Dilation, Gaze & Eye Tracking, & FP-View Camera



Empatica E4

Measures Heart Rate Variability & Skin Conductance

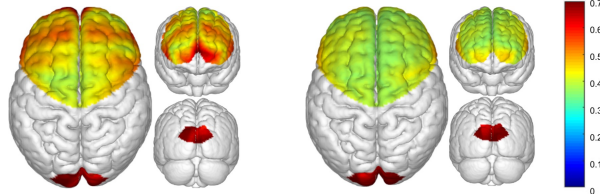


Brain Activity



- Unbiased, objective, and continuous
- Why fNIRS/EEG? Cost effective, and ambulatory data collection in naturalistic settings
- Neural correlates of trust

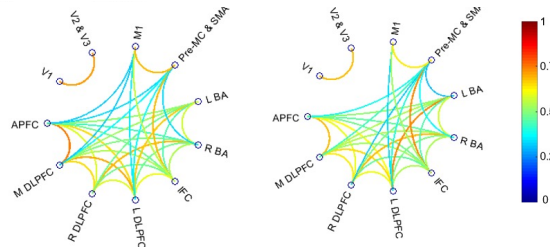
Brain Activations



Reliable

Unreliable

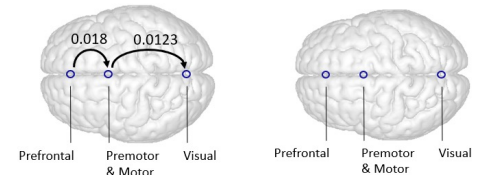
Functional Connectivity



Reliable

Unreliable

Effective Connectivity



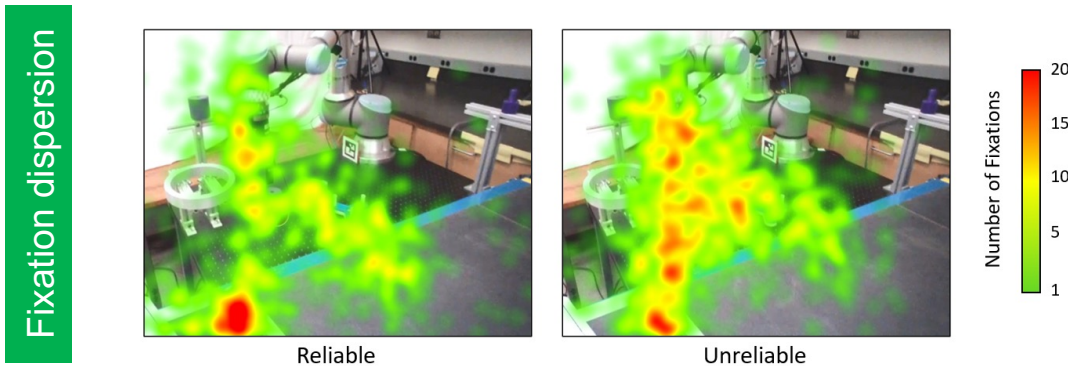
Reliable



Eye-tracking



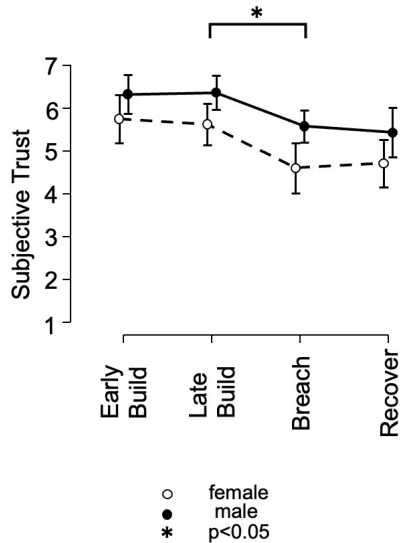
- Types of eye-movements: **gaze**, **saccade**, and **fixation**
- **Bottom-up**: stimulus that attract fixations independent of the internal state of an observer.
- **Top-down**: cognitive influences on the chosen fixation locations based on the current aims of an observer



Eye-tracking: Gaze entropy

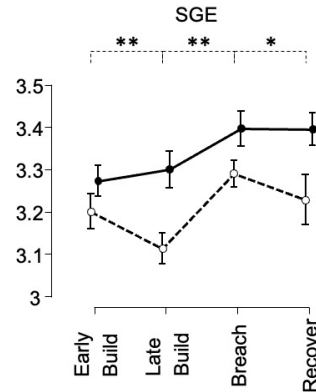


Subjective trust



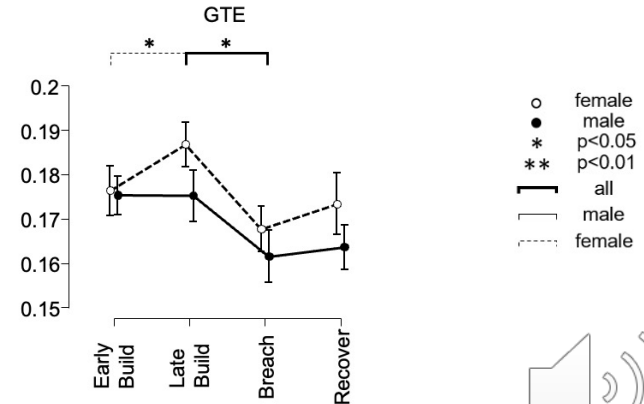
Stationary Gaze Entropy (SGE)

- Estimates overall spatial dispersion of gaze

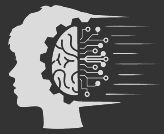


Gaze Transition Entropy (GTE)

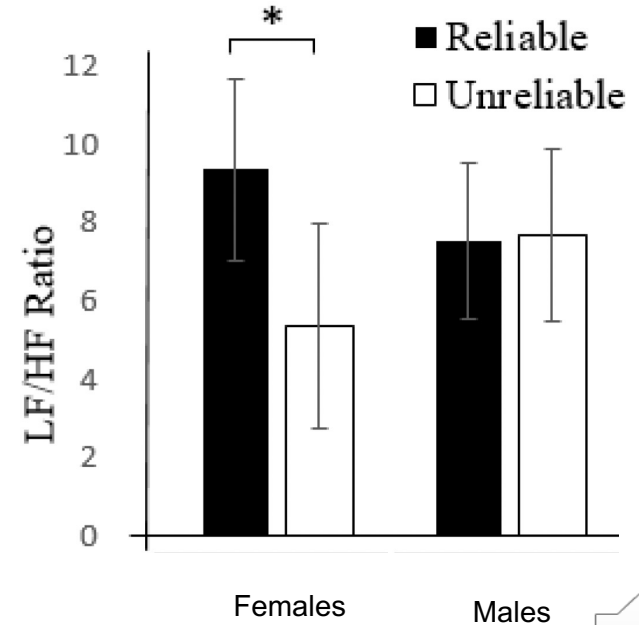
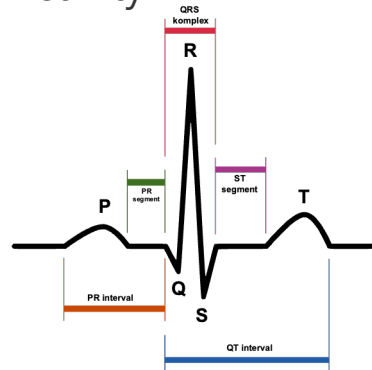
- Estimates uncertainty when predicting the next fixation location given the current fixation



Heart Rate Variability (HRV)



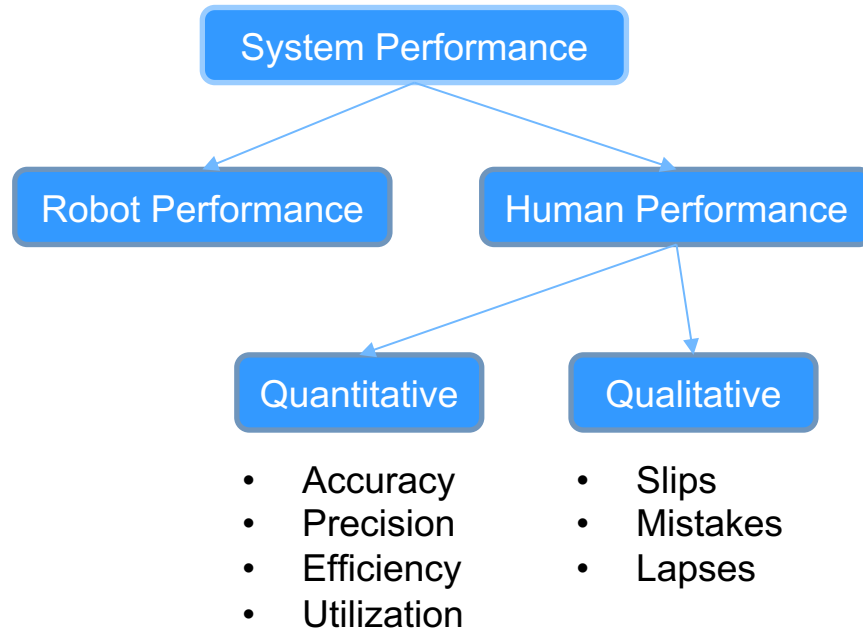
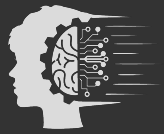
- Insight into parasympathetic and sympathetic nervous systems
- Frequency domain HRV
 - HF – Parasympathetic Activity
 - LF & VLF – Sympathetic Activity
 - LF/HF ratio



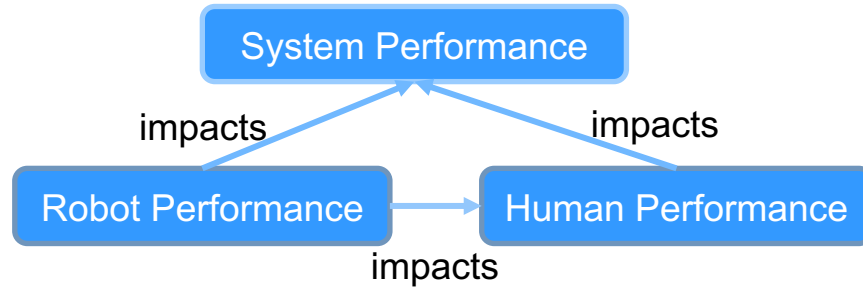
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Performance and Behavior Delineation



Performance and Behavior Delineation



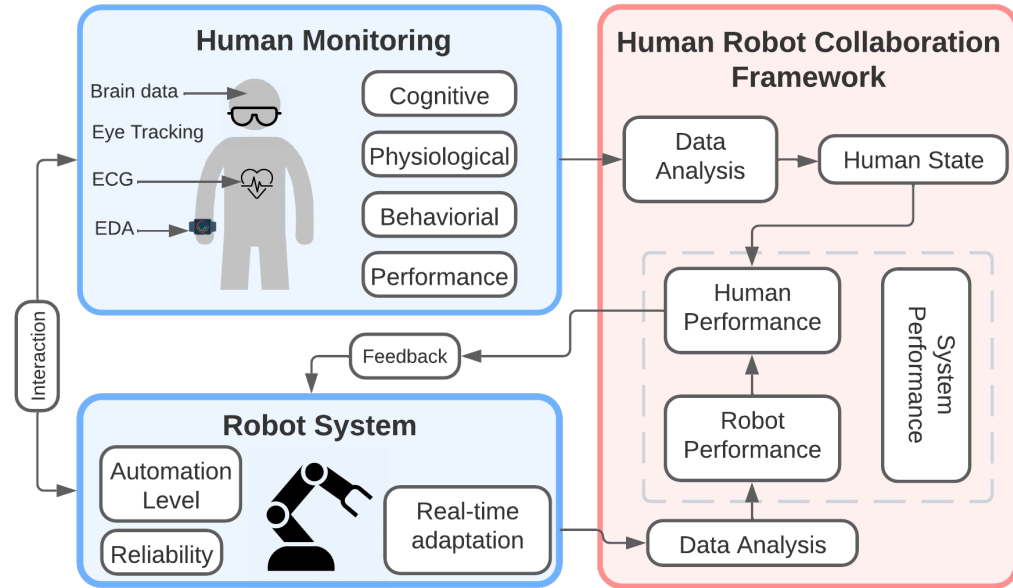
- Robot performance impacts human performance
- Transparency in robot performance is critical



Implications



- Improved understanding of HRC
- Near real-time robot adaptation
- Personalized interactions
- Reduction in cognitive load and worker fatigue
- Improved system performance



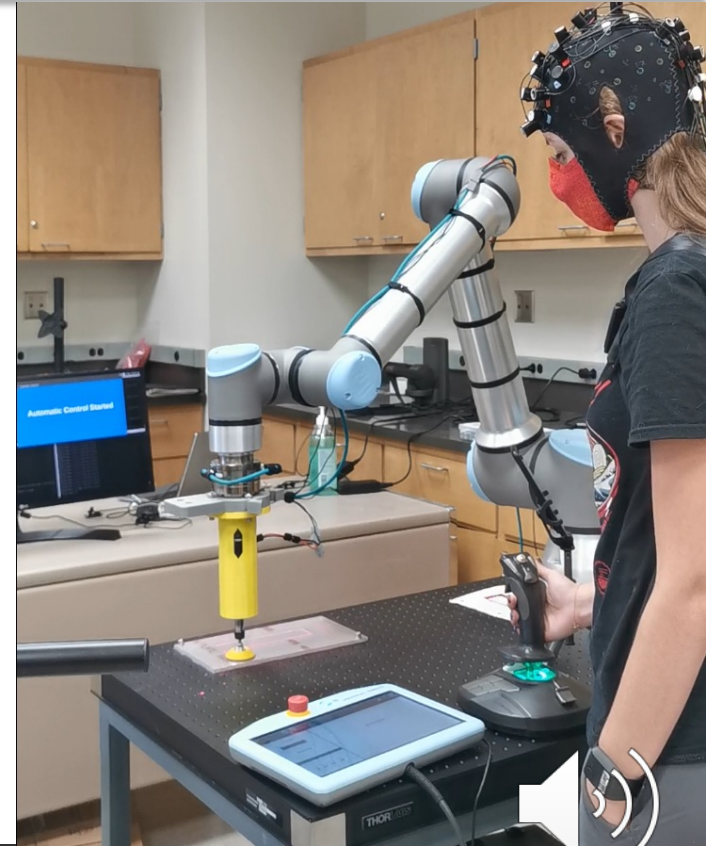
Conclusion

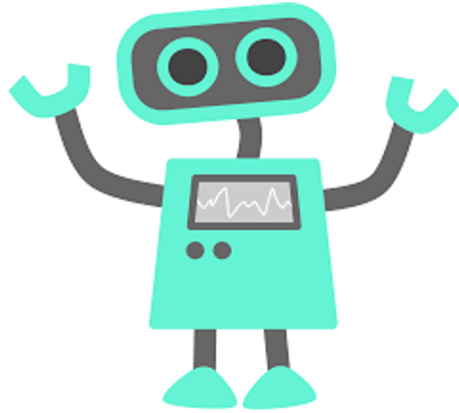


Multimodal Bio-Behavioral measures can objectively account for trust

Humans are inherently different from one-another and their behaviors are transient

Physiological measures allows for in-situ robot adaptation





Questions?



Relevant work



- Hopko, S., Wang, J., & Mehta, R. (2022). Human Factors Considerations and Metrics in Shared Space Human-Robot Collaboration: A Systematic Review. *Frontiers in Robotics and AI*, 9.
- Hopko, S. K., & Mehta, R. K. Neural Correlates of Trust in Automation: Considerations and Generalizability Between Technology Domains. *Frontiers in Neuroergonomics*, 26.
- Hopko, S. K., Mehta, R. K., & McDonald, A. D. (2021, September). Trust in Automation: Comparison of Automobile, Robot, Medical, and Cyber Aid Technologies. In *Proceedings of the Human Factors and Ergonomics Society Annual Meeting* (Vol. 65, No. 1, pp. 462-466). Sage CA: Los Angeles, CA: SAGE Publications.

